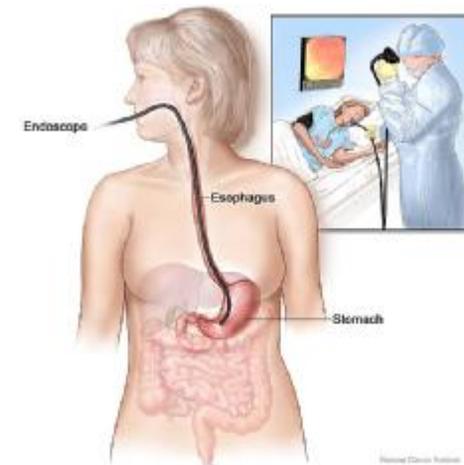




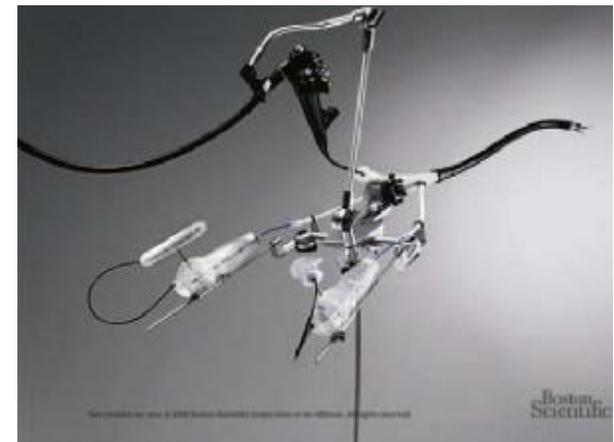
TeleFLEX

Design of Master for Tele-manipulation System for Endo-/Transluminal Endoscopic Surgery



Jitendra Prasad Khatait

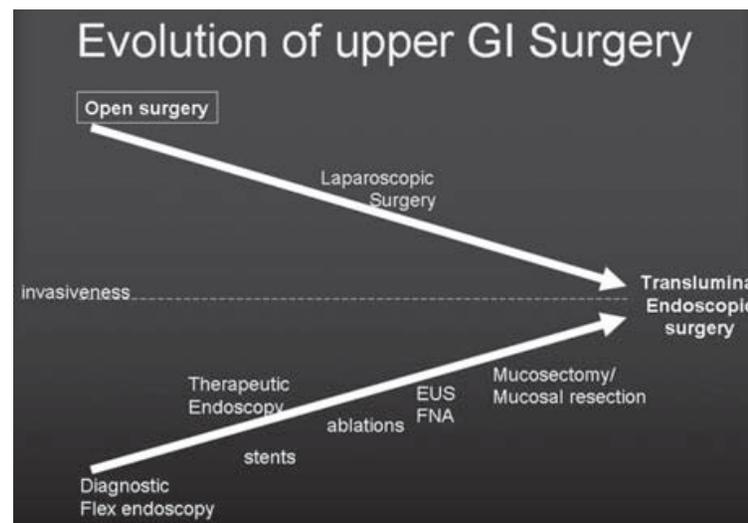
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Convergence of technologies

- *Minimal Invasive Surgery (MIS) is becoming less invasive*
- *Endoscopy is becoming more invasive*





Requirements

- Stability
- Triangulation
- Maneuverability

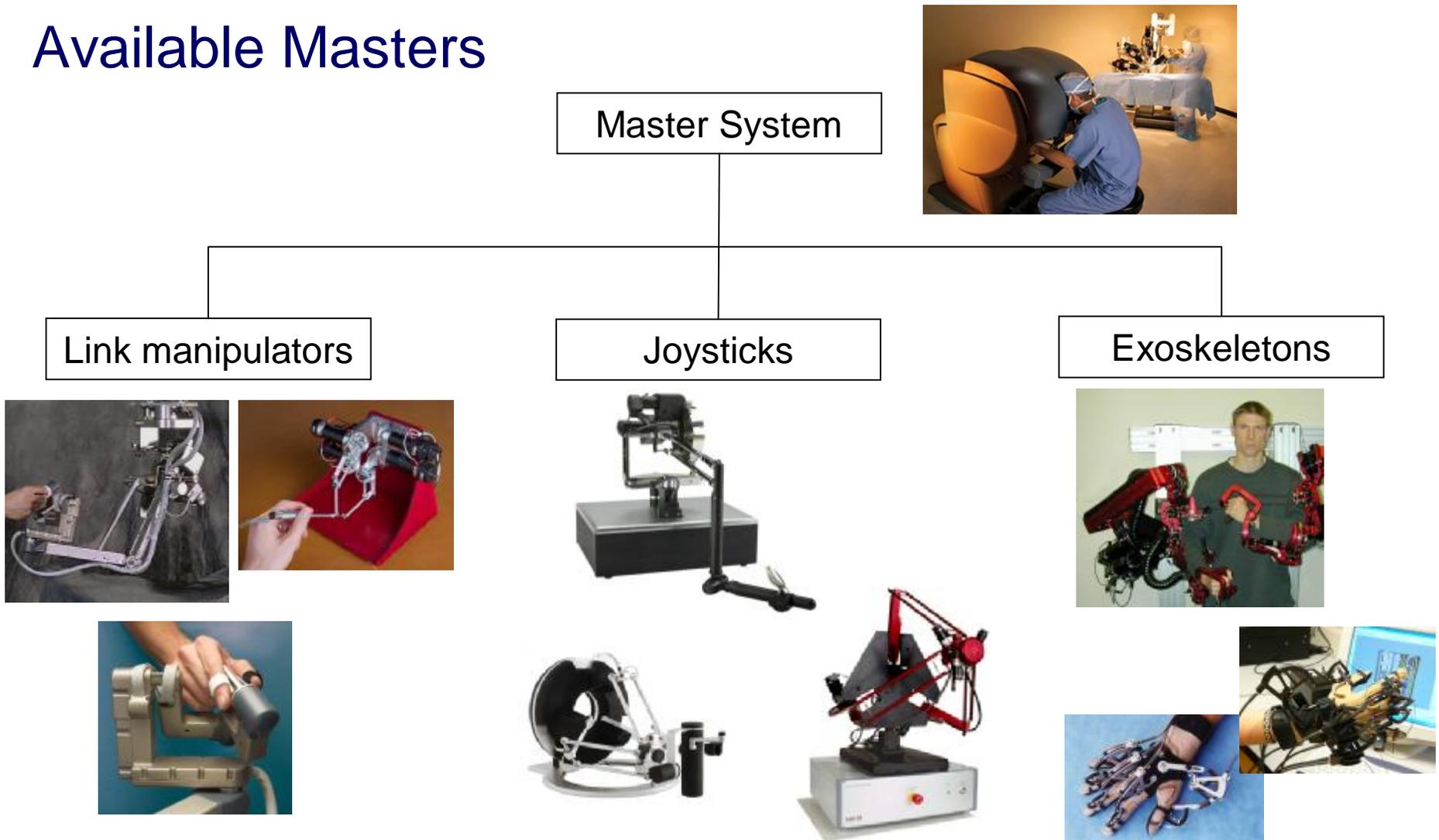


Development of a multi-tasking platform





Available Masters





What Next ???

Goal:

Design of Master for Tele-manipulation System for Endo-/Transluminal Endoscopic Surgery

Approach:

Research on Mechanical Design Aspects of Surgical Robotic Systems

Research areas:

- ✓ *Kinematic Design*
- ✓ *Transmission and Drives*
- ✓ *Dynamics*
- ✓ *Dexterity and Working Space*



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Thanks for your attention !!!

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